

POWERED EXOSKELETONS

Team LeftOvers

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JUSTIFICATION [1]

- **Military personnel required to carry large amounts of gear**
 - Currently carries 100 pounds
 - Chronic back injuries
- **Wheelchair patients**
 - 1% of the world's population in wheelchairs



<http://www.screenhead.com/reviews/iron-man-review-stark-entertainment/>

OUTLINE

- History of exoskeletons
- Civilian uses for exoskeletons
- Military uses for exoskeletons
- Road ahead
- Conclusions



<http://www.dailymail.co.uk/sciencetech/article-1049215/Paralysed-man-walks-thanks-Robocop-style-exoskeleton.html>

HISTORY [2,3]

• Hardiman

- Developed by Ralph Mosher, an engineer for GE, in the 1950's
- Consisted of powered arms and legs
- GE had high hopes for the exoskeleton robot



• Developments

- 1987: Lifesuit
 - Developed by Monty Reed, who started work on it for physical therapy
- 1990: Power Assist Suit
 - Japan's Kanagawa Institute of Technology

<http://www.adafruit.com/blog/2010/09/08/ges-retro-exoskeleton-robot-from-the-1950s/>
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HISTORY [3]



<http://www.popsoci.com/scitech/gallery/2008-04/brief-history-exoskeletons>

- **2002: Hal-3**

- Developed by Japanese company, Cyberdyne, to help nurses carry patients. Late, Hal-5 was released

- **2004: Bleex**

- Berkeley's Lower Extremity Exoskeleton



<http://www.popsoci.com/scitech/gallery/2008-04/brief-history-exoskeletons>

- In 2001, DARPA started to lead in the development with 3 contractors
- In 2004, Sarcos Research Company was selected as the finalist
- Sarcos has developed 3 main systems, and continues to research

HONDA: BODY SUPPORT ASSIST [4],[5]



- Function
 - Reduce stress on legs and knees
 - Provide Partial body weight support
- Height 160 to 180cm
- Lithium ion Battery
- 2 hour Operating Time
- 2 motor drive system

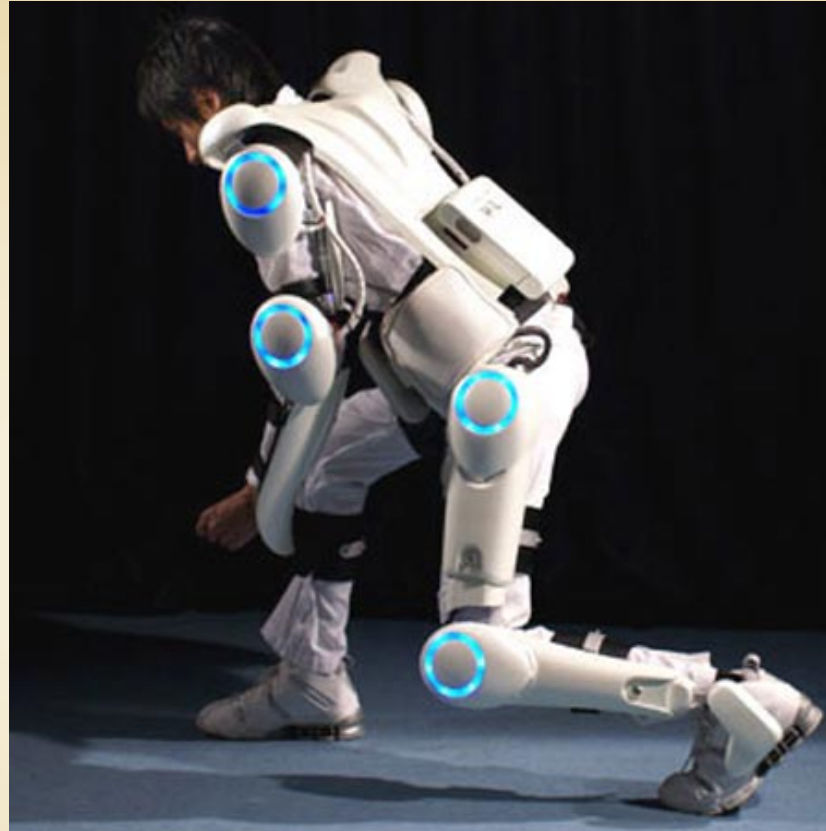
BODY SUPPORT ASSIST [6],[8]



www.Honda.com

- Unique Innovation
 - directs the assisting force toward the user's center of gravity
 - Varying assisting force to the legs based on sensor information
 - Increases assisting for higher degrees of knee rotation

CYBERDYNE: HYBRID ASSISTIVE LIMB [7]



http://www.cyberdyne.jp/english/robot_suit/hal/index.html

Robot Suit HAL moves in accordance with the wearer's intention

CYBERDYNE: HYBRID ASSISTIVE LIMB [9]



- Voluntary control system
 - Bio electric signals are picked up with sensors on the skin
 - Signals are analyzed by a computer
 - Power unit sends a signal to compliment the wearers muscle movement
- Robotic Autonomous Control

SPECS [9]

- Height – 1.4 to 1.6m
- Weight 23Kg
- Power-
Rechargeable
Batter (100V)
- Operation Time –
2hrs 40 mins
- Indoor/Outdoor use



<http://androidlives.com/ces-2011-polaroid-square-tablet-trying-to-fit-in-a-round-peg-ces-polaroid-square-shows-off-tablet-android-ces-goers/>

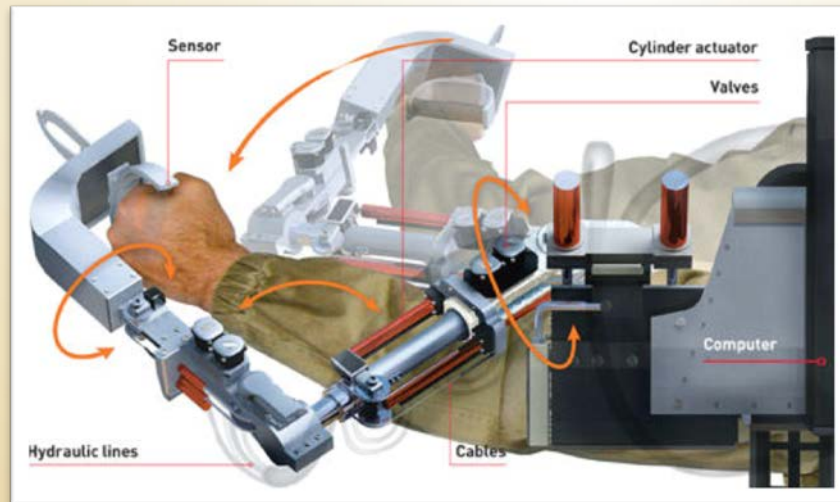
MILITARY USES



<http://www.ironman2.net/>

MILITARY USES [10]

- Raytheon XOS
 - Funded by DARPA
 - 150 lb
 - 200 lb feels like 10 lb
 - 30 hydraulic actuators



MILITARY USES [11]

- Human Universal Load Carrier (HULC)
 - Berkeley Bionics and Lockheed Martin
 - Can take 200 lb without hindering wearer
 - 81 lb at 2 MPH decreases overall oxygen use by 15%
 - Powered by battery pack
 - LCD screen controls
 - Adjustable



<http://bleex.me.berkeley.edu/>

FUTURE [12]

Future depends on developing new technologies to remedy certain problems.

- Power Source
- Structural Materials
- Control
- Actuation
- Biomechanics
- Stealth

CONCLUSIONS

- **Powered exoskeletons have the potential to change battlefield technology forever**
- **Paraplegic patients may leverage new technologies to walk again**
- **Future exoskeletons will better integrate with humans, blurring the line between man and machine**

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- [3] "A Brief History of Exoskeletons," 2008, Popular Science, from <http://www.popsci.com/scitech/gallery/2008-04/brief-history-exoskeletons?image=0>.
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QUESTIONS?

